

A MODULAR MACHINE MONITORING AND DIAGNOSTIC SYSTEM FOR DIESEL-DRIVEN MINING VEHICLES

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ABSTRACT: Mining vehicles are often driven by a diesel engine and a power transmission with hydrostatic or hydrodynamic subsystems. The development of a machine monitoring system was initiated by several investigations of failure distributions of monorail diesel trolleys, which pointed out that these main components are causing most breakdowns or the major portions of the maintenance costs. Furthermore the analysis of maintenance activities in a German hard coal mine uncovered that the annual maintenance costs of a monorail diesel trolley make 43 per cent of the vehicle's new price and for nearly one third of the repairs the failure was not recognised while the vehicle was in the maintenance shop for the first time. Condition monitoring is a suitable method to assist the workshop staff in finding defects and to maintain equipment in a more efficient way. To support condition-based maintenance of diesel-hydraulic drives a modular machine monitoring and diagnostic system has been applied to monorail trolleys, mining locomotives and recently shovel loaders. It is generally adaptable to all kinds of diesel-driven vehicles. The systems architecture will be presented by its first-time application in a German hard coal mine, where it is part of a more complex maintenance planning system. The focus will be on the features for engine diagnostics. New diagnostic experiences with turbocharged diesel engines which are common in surface vehicles will help to adapt (the system to surface applications with state of the art supercharged diesel engines).

I INTRODUCTION

In the production process and in those fields that help maintain European mining operations, diesel-powered vehicles are often used. Their task is to transport the debris produced, for example coal, ore, salt, as well as to handle the materials needed for production. Particularly in underground mining the transport of materials is very important.

Investigations of the running expenses of diesel-powered transport vehicles in the German coal mining industry disclosed that the annual costs for maintenance and repair work of a single vehicle can be up to 43 per cent of its cost price. The study also showed that during the two years of observation it took on average one half of a shift to complete the maintenance of a monorail diesel trolley. Although up to two out of three shifts were spent on the maintenance of these vehicles, defects or even breakdowns occurred between the ninth and fourteenth shift on duty. The analysis of the maintenance strategy led to the conclusion that due to the fixed maintenance intervals the actual condition of the vehicles was ignored and the repair work was earned out only

after defects had occurred. In summary, the study concluded that in terms of utilisation the maintenance costs were too high (Linnartz, 1992).

On a more technical level these investigations identified those components which most often are responsible for a vehicle breakdown and derived the related distribution of the total maintenance costs (wages and costs of replacement parts) of each subsystem (Fig. 1). The distribution shows that reasonable savings may be realised by focusing on the subsystems of hydraulic power transmission and diesel engine.

The need of a high availability and minimal maintenance costs of the mining vehicles studied requires a change of the maintenance strategy to a condition-based maintenance, where the extent and time of maintenance depend on the actual state of the machine. To determine the condition of the vehicle's subsystems and its components a computer-based diagnostic system called RUDI was developed. RUDI is an abbreviation for 'Lechneiuileistutztes Diagnosesystem für die hydraulische Antriebe', which is

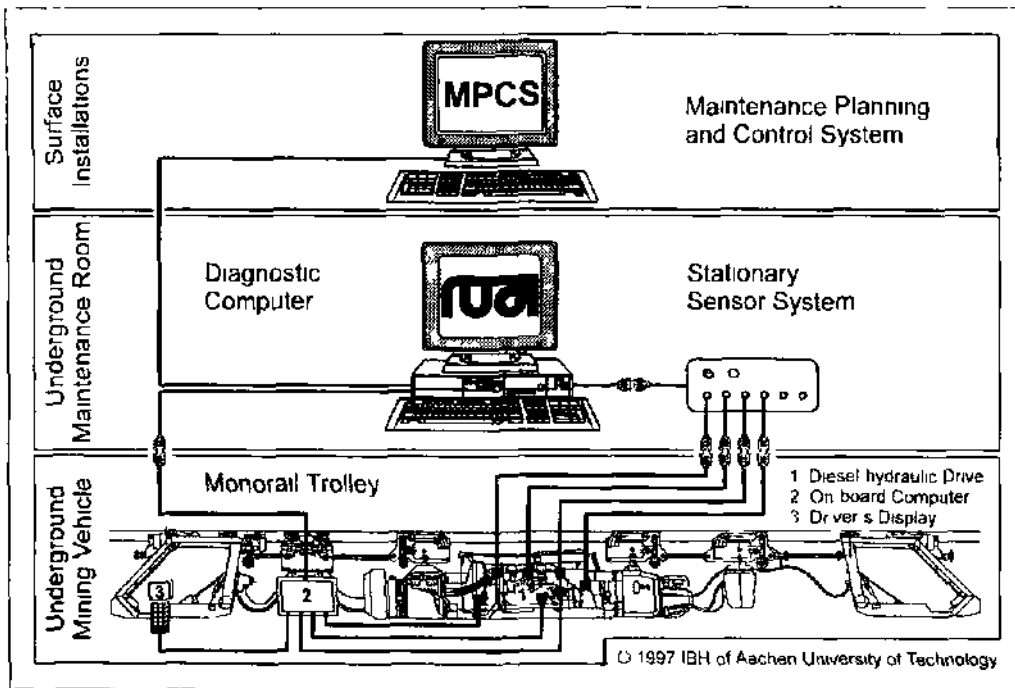


Fig 2 System overview I - diagnostic system as a part of a maintenance planning, and control system for transport vehicles in underground mining

the vehicle's utilisation and to calculate maintenance intervals

The stress of the diesel engine is determined and recorded from the engine torque and the exhaust gas

temporal estimation of the engine's efficiency is possible if electronically controlled injectors are available. First operational experiments were carried out with four monorail diesel trolleys that have been equipped with an on-board computer and sensors to monitor the utilisation of the diesel engine and the hostal transmission. An evaluation of the load data recorded during the monitored unit indicates that the transmission is almost always operating at low power.

Oil change intervals are determined on the basis of stress. The results can be shown on the display.

Oil change intervals can be determined

with high resolution by means of the

tact displacement sensors when the engine is spun by the starter (cold test) or during firing operation (hot test). From an analysis of the harmonic orders after the highest measurement, a general statement on the engine's condition can be made.

By balancing the measured values with the calculated proximate values of the gas load, the speed variation of the engine is used for the determination of the engine's condition (Streithaus, 1997).

The variation of the engine's condition is measured by means of the piezoelectric sensors. Although these sensors are not able to detect the pressure fluctuations in the oil, the pressure at the inlet of the oiler is measured. The pressure at the inlet of the oiler is measured by means of the piezoelectric sensors. The pressure at the inlet of the oiler is measured by means of the piezoelectric sensors. The pressure at the inlet of the oiler is measured by means of the piezoelectric sensors.

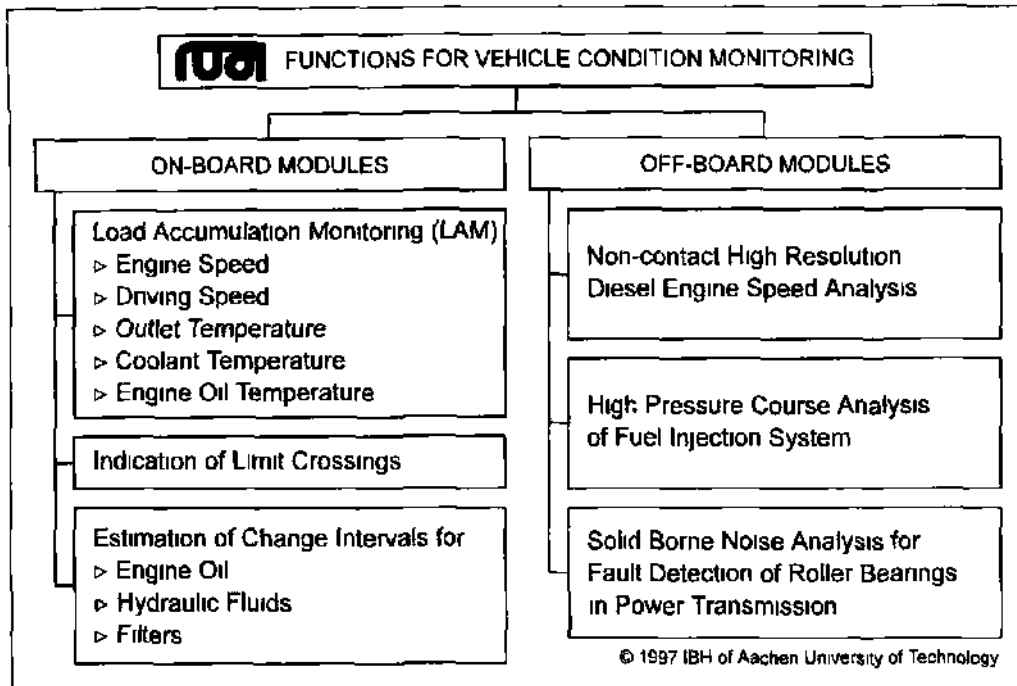


Fig 3 System overview *il* - applied monitoring and test functions

condition of the fuel injection system for example faulty settings or wear in the pump and nozzles

A diagnostic module for condition monitoring of a converter's rotating components particularly the damage-endangered roller bearings and gearwheels is optionally available. It is based on the analysis of solid-borne noise signals that are recorded by extremely low-priced and robust acceleration sensors - so called knock sensors - which are used in the automobile industry for detecting malfunctioning combustion

The subsequent signal processing forms a *diagnosis* characteristic by means of an envelope curve analysis. This method assists in diagnosing the bearing damage even in complex systems for example on a diesel rail s converter (Keßler 1994)

2.1 Maintenance support with an expert system

The expert system provides an effective support for the maintenance staff in finding machine faults. The implemented knowledge concerning specific problems of the vehicle (for example the controls of diesel engines and hydraulic pumps) is available to all

workers. They can communicate with the expert system via the underground diagnostic computer. Special knowledge-bases serve to analyse the signals from high-pressure monitoring, solid-borne noise measurement and non-contact torque monitoring. On the basis of the machine history (administered by the expert system) weak points in machine maintenance use and construction can be meaningfully analysed.

The fact that the implemented rules take the installation date of the parts into consideration is important because technicians working on three different shifts often are not aware of work completed in previous shifts and unnecessarily inspect parts of subsystems that have already been checked (Wischnewski et al. IWS)

2.4 Interfile diagnostic system/MP(S)

The diagnostic results are a need for maintenance work to be carried out. This may be either a repair, a service or a further detailed inspection. This requirement triggers the activities supported by the MPC(S). In order to lengthen the planning period and increase the planning quality, the information is automatically sent to the MP(S) as a rudimentary work order.

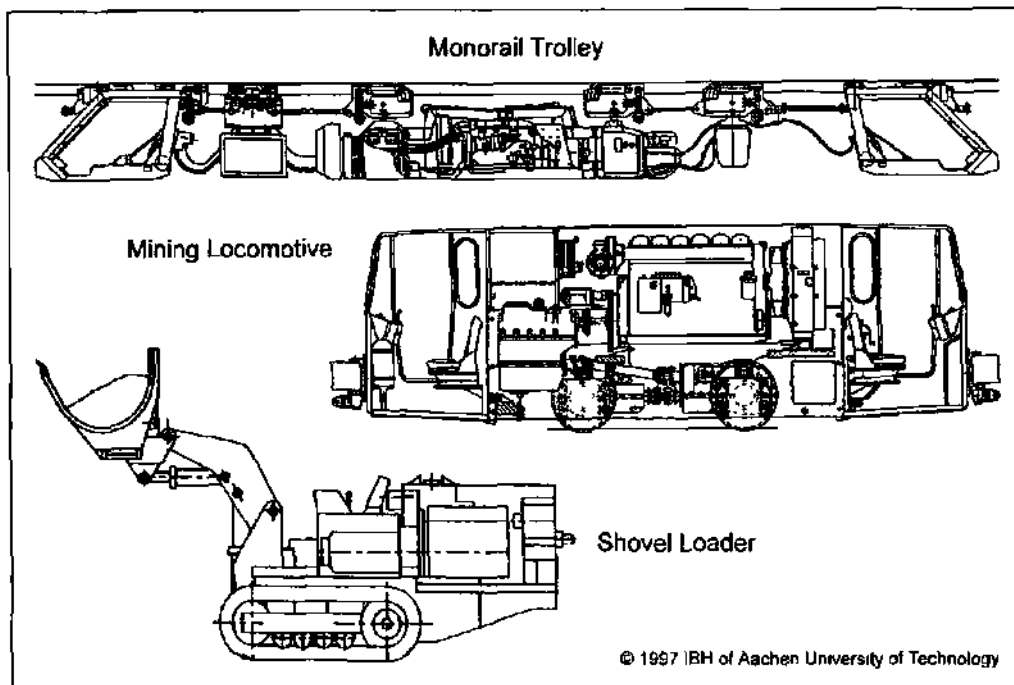


Fig 4 A selection of mining vehicles monitored by RUDI

containing -vehicle number, job plan number and priority. The maintenance planner, using the MPCS, fills in the remaining work order information: worker data, date and spare parts involved, and approves the work order. The planned date and duration of maintenance are sent to the vehicle dispatching. Using a common database for the expert system and the MPCS, redundancies and contradictions in data stocking are avoided. Via a computer network, the approved work orders are passed on to the corresponding underground diagnostic computer, where they are indicated to the workers. While carrying out the job, the worker can retrieve information from the MPCS about job plans or technical data about the vehicle. Having completed the job, the worker uses the diagnostic computer directly for confirmation of the work order; this is subsequently sent to the MPCS (Wischniewski et al. 1996).

3 ENGINE DIAGNOSTICS RESEARCH DUE TO THE DEMANDS OF SURFACE VEHICLES

Although meeting special requirements of vehicles in the underground mining (Fig 4), the presented system can be adapted for other industrial applications

and some diagnostic modules have already been adapted for a surface application, namely a rail car on a private German rail company. For further diversification into surface vehicles, for example heavy duty trucks in the mineral industry or cargo trucks, the engine diagnostic functions will become more important. A comparison of the failure distribution of monorail diesel trolleys with the one produced by road cargo trucks (Dumoulin and Burgwinkel, 1991) points out that the diesel engine is of major interest if no hydrostatic or hydrodynamic power transmission belongs to the vehicle (Fig 5).

A technical argument for increasing importance of engine diagnostic methods is given by the fact, that most surface transport vehicles in the future will be equipped with supercharged diesel engines. This is due to their better torque characteristics, their lower exhaust emissions and a better power-to-mass ratio compared to naturally aspirated diesel engines.

There are three main methods for supercharging of combustion engines, namely mechanical charging by compressors, turbo-charging by exhaust-driven superchargers and charging methods working without any compressor, for example pressure wave charging.

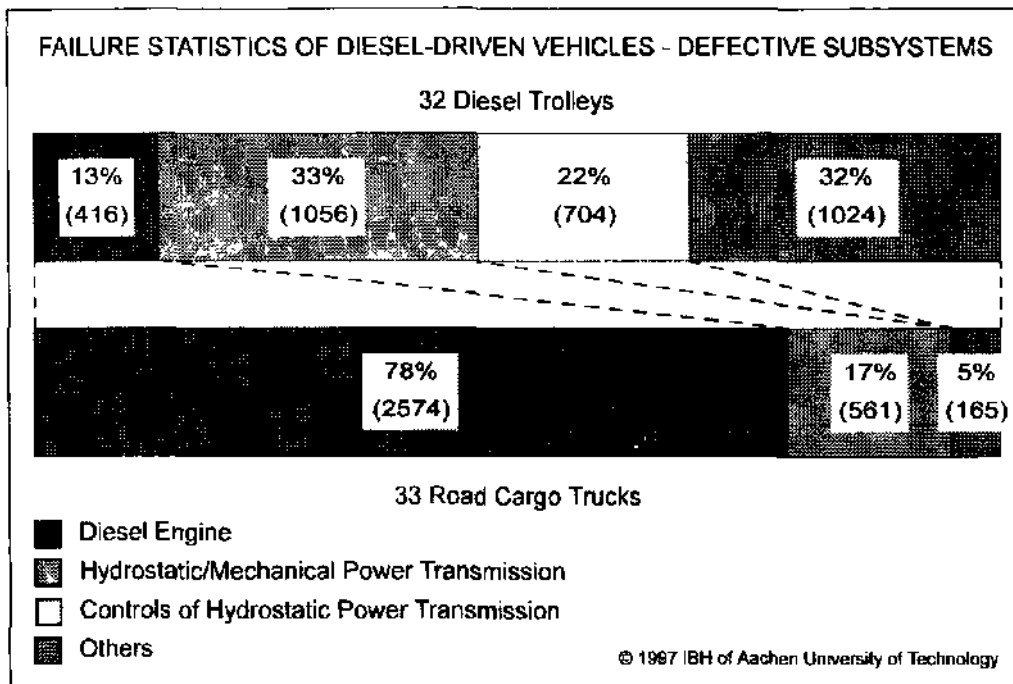


Fig 5 Comparison of failure distributions of different types of diesel-driven transport vehicles.

(complex method) and resonant charging Turbo-charging is the most important one

Condition monitoring in general deals with the detection of a fault's kind and severity as well as the identification of the faulty component in a complex engine. Reduced power of diesel engines is most often caused by compression faults, for example by maladjusted valve settings and worn piston rings, or malfunctioning components of the fuel injection system. To detect these faults engine tests are usually made during steady-state operating modes - and so does RUDI. Compression faults are detected by high resolution speed analysis during cold tests. Faults of the injection system are detected by hot tests (idle speed) using high pressure analysis and suitable diagnostic parameters based on high resolution speed measurements. To identify defective cylinders different cylinder-specific parameters are available, for example the alternating amplitude of the gas torque (see also 2.2) the velocity index or the acceleration index. Their common attribute is that they are used for steady-state operating mode* of the engine.

3.1 Experimental results from steady-state hot tests

Recent trials on a test stand with an impulse-charged V-6 diesel engine with intercooling proved that obstructive interactions - with regard to cylinder-specific evaluation of the engine's condition - between faulty and intact cylinders may occur. During tests when the engine was running at idle speed with a severe fault at a single cylinder (no fuel condition) an evaluation of the velocity index implied that there are two defect cylinders (Asch and Burgwinkel, 19%). However RUDI is able to identify the single faulty cylinder by means of high pressure analysis of the injection system.

These experiments demonstrate that diesel engines with exhaust-driven supercharger, need more sophisticated methods for speed-based engine diagnosis during hot tests, because inlet and outlet system are linked by the turbocharger. Particularly those with impulse charging are more demanding with regard to cylinder-specific diagnosis because the cylinders performance may be influenced by another one.

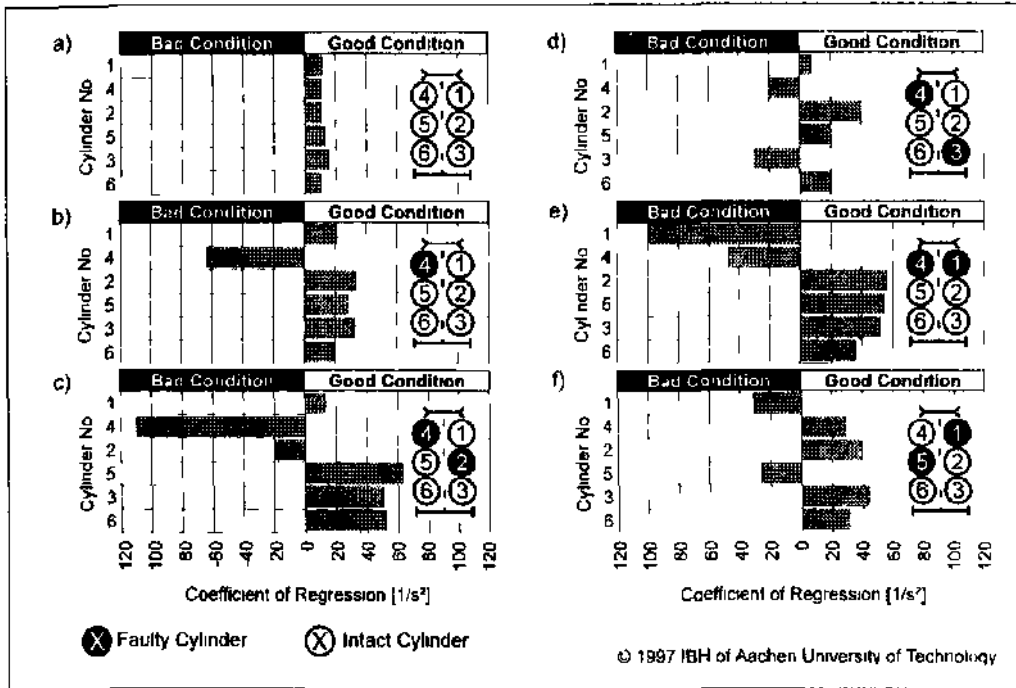


Fig 6 Cylinder-specific fault detection on an impulse-charged diesel engine by snap acceleration tests

3.2 Experimental results from acceleration tests

Much better cylinder-specific fault detection with the impulse-charged diesel engine could be reached by performing snap acceleration tests. In free acceleration mode (no external load, maximum fuel) the engine is run from idle to limit speed. When the engine speed crosses a pre-defined trigger-level, a high resolution speed measurement is carried out.

Speed data from these tests are evaluated as follows: A window containing speed data of one cycle (two rotations on a 4-stroke-engine) is cut into z intervals where i represents the total number of cylinders. Each interval consists of the expansion phase of a single cylinder and the compression phase of the other cylinders. The firing sequence (1-2-3-4) is used. In the expansion interval, the parameters of a regression line are calculated. Intact cylinders have a positive slope of the regression line, whereas negative slopes indicate faulty cylinders. Using this method, positive results (Fig. 6) were gained not only with single faulty cylinders but also with different combinations of faulty cylinders (at most).

1.1 Engine compression test for surface vehicles

Because of safety requirements, diesel-driven underground vehicles in coal mining are equipped with pneumatic starters. Diesel engines in surface vehicles have electric starters with DC start motors. Their motor current is closely linked to MIL (Maximum Idle Load) and easily to measure by Hall-effect sensors. Therefore, the motor (instead of dynamic compression tests) (Kiciriloic and Kiswloil, 1995) can be used for stand-alone diagnosis based on the measurement of the motor current. The ability as it is based on high resolution speed measurement.

Fig. 7 shows an example of the results on the 5-cylinder engine. The motor current is measured during the compression phase of cylinders 4 and 5. The evaluation of the results is shown in Fig. 8. The evaluation of the results is shown in Fig. 8. The evaluation of the results is shown in Fig. 8.

4. CONCLUSIONS

Investigations of the engine compression test for surface vehicles are shown in Fig. 8. The evaluation of the results is shown in Fig. 8.

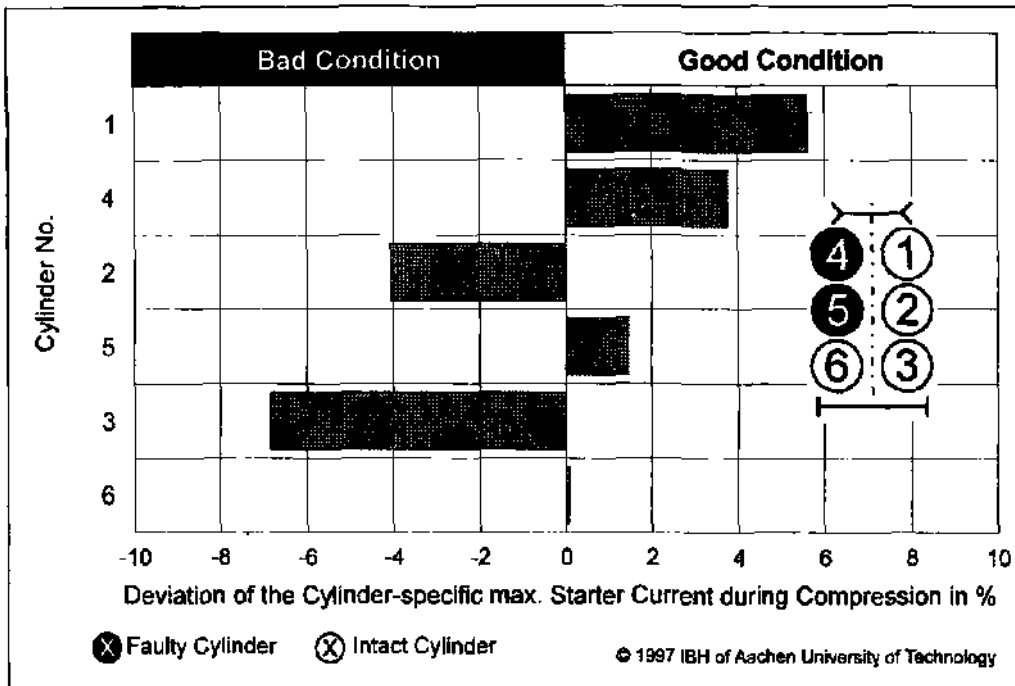


Fig 7 Cylinder-specific fault detection on multi-cylinder engine by evaluation of starter current.

able potentials for lowering of maintenance costs by a condition-based maintenance strategy. To get the necessary information about the condition of a vehicle's most interesting subsystems, namely the diesel engine and the hydraulic power transmission, a modular vehicle diagnostic system has been developed, that is good for mining. It supports the maintenance staff by offering diagnostic knowledge by an integrated expert system and by data exchange with a maintenance planning and control system.

Although meeting the special requirements of transport vehicles in the coal mining, the presented system is principally capable to support equipment maintenance management and performance monitoring of all kinds of vehicles with diesel-hydraulic drives.

Transfer of the system to surface vehicles means to diagnose turbocharged engines, which are due to their greater complexity more demanding concerning high resolution speed analysis than naturally aspirated diesel engines. Experiments with a state of the art impulse-charged diesel engine proved that deterioration of cylinder-specific performance is more reliably detected during acceleration tests than during steady-

state tests. Considering these results the diagnostic modules will be extended.

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